

Dijkstra Goes Random

Weakest-Precondition-Reasoning on Probabilistic Programs

Joost-Pieter Katoen




The 20th KeY Symposium, July 2024



Probabilistic programs

Programs with **random assignments** and **conditioning**



```
{ w := 0 } [5/7] { w := 1 };  
if (w = 0) { c := poisson(6) }  
else { c := poisson(2) };  
observe (c = 5)
```

probabilistic branching

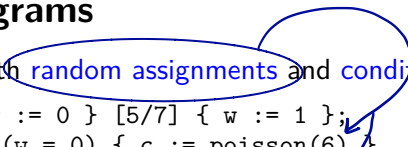
$$\Pr \{ w=0 \} = \frac{5}{7} \quad \Pr \{ w=1 \} = \frac{2}{7}$$

¹[Gordon, Henzinger, Nori and Rajamani, FOSE 2014]

Probabilistic programs

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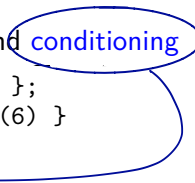
A blue oval highlights the text "random assignments and conditioning". A blue arrow points from the "observe" statement to the "if" statement. Another blue arrow points from the "if" statement to the "else" statement.

¹[Gordon, Henzinger, Nori and Rajamani, FOSE 2014]

Probabilistic programs

Programs with random assignments and conditioning

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They encode:

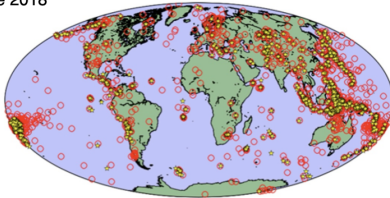
- ▶ randomised algorithms
- ▶ probabilistic graphical models beyond Bayes' networks
- ▶ controllers for autonomous systems
- ▶ security mechanisms
- ▶

"Probabilistic programming aims to make
probabilistic modeling and machine learning accessible to the programmer."¹

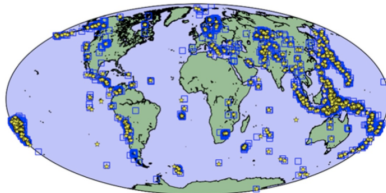
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"Real" Examples

before 2018



since 2018

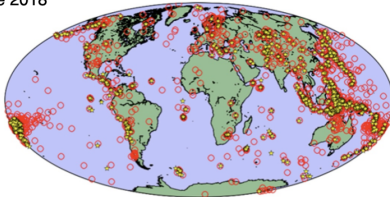


the UN diagnoses seismic events
using probabilistic programs

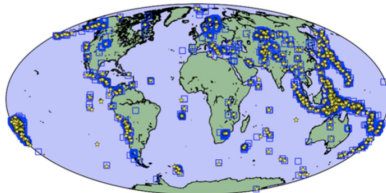
[Arora *et al*, Bull. Seism. 2017]

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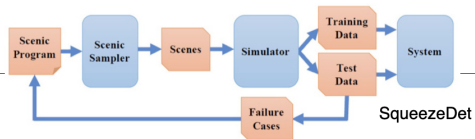


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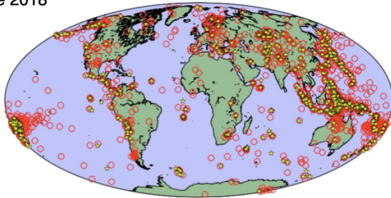
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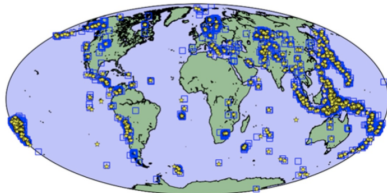
SCENIC generates more effective training sets
[Fremont *et al*, Mach. Learn. 2023]

"Real" Examples

before 2018

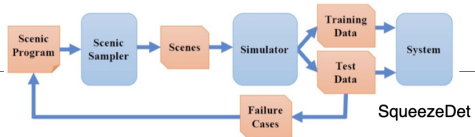


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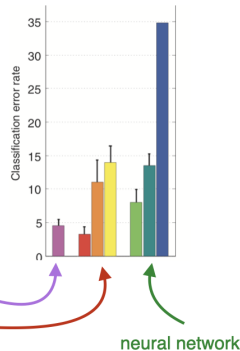
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சு	அ	ர	பு	து
இ	த	ன	த	வ
ந	ய	ல	க	பு



STAN, PyMC,
Edward, Pyro,
ProbLog, WebPPL

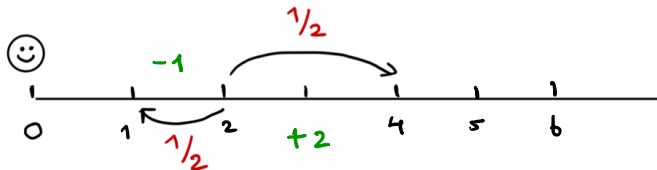
[Lake *et al*, Science 2015]

Probabilistic programs are hard to grasp

Does this program **almost surely terminate**? That is, is it **AST**?

```

x := 1;
while (x > 0) {
  x := x+2 [1/2] x := x-1
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x := 1;  
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If not, what is its **probability to diverge**?

Even if all loops are bounded

[Flajolet *et al*, 2009]

```
x := geometric(1/4);
y := geometric(1/4);
t := x+y+1 [5/9] t := x+y;
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  }
  r := (s == t)
}
```

What is the probability that r equals one on termination?

Positive AST

```
int x := 1;
bool c := true;
while (c) {
  c := false [0.5] c := true;
  x := 2*x
}
```

Finite expected termination time?
aka: is this program positive AST?

Positive AST

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int x := 1;  
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```
while (x > 0) {  
    x := x-1  
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```

Finite termination time!
PAST.

Positive AST

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Finite expected termination time?
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•
;

```

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Expected runtime of these programs in sequence?

Positive AST

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Finite expected termination time?
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•
;

```
while (x > 0) {
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Finite termination time!
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Expected runtime of these programs in sequence?

∞

$PAST(P) \wedge PAST(Q) \not\Rightarrow PAST(P; Q)$

Our objective

A powerful, simple proof calculus for probabilistic programs.

At the source code level.

No “descend” into the underlying probabilistic model.

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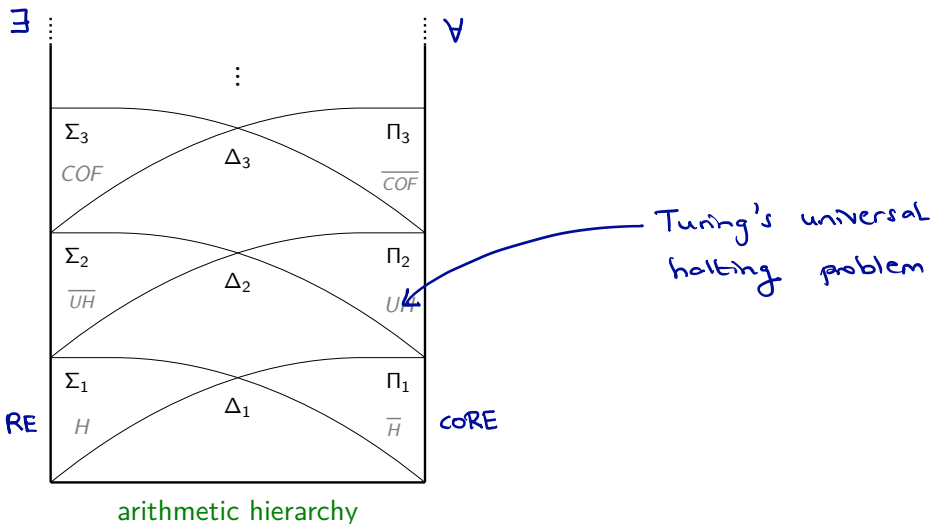
No “descend” into the underlying probabilistic model.

Push **automation** as much as we can.

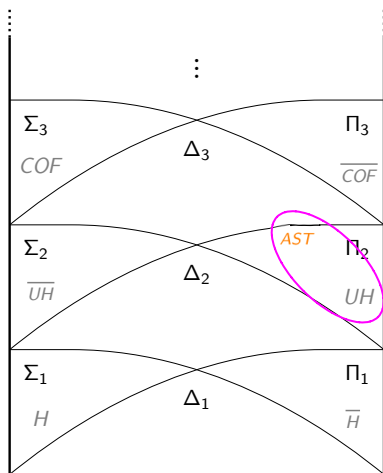
This is a true challenge: undecidability!

Typically “more undecidable” than deterministic programs

Probabilistic programs are “more undecidable”



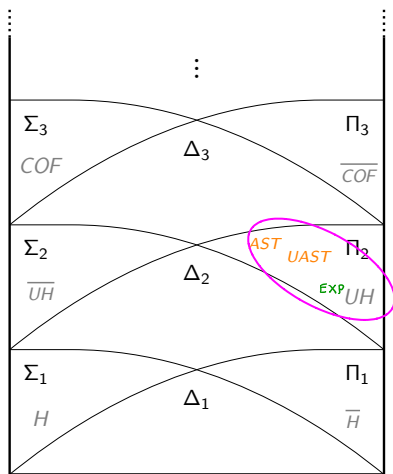
Probabilistic programs are “more undecidable”



arithmetic hierarchy

AST for **one** input
is as hard as
the halting problem for **all** inputs

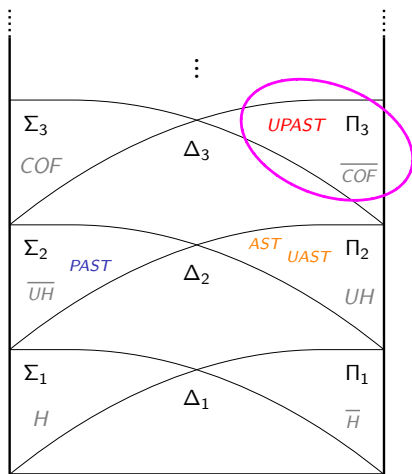
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Probabilistic programs are “more undecidable”



arithmetic hierarchy

AST for **one** input
 is as hard as
 the halting problem for **all** inputs
 is as hard as
 computing expected outcomes
 but

deciding finite expected runtime?
 is “**even more undecidable**”

[Kaminski, K., MFCS 2015]

Roadmap of this talk

Part 1

- ▶ Probabilistic weakest preconditions

Part 2

- ▶ Proof rules for probabilistic loops

Part 3

- ▶ Relative completeness and automation

“Dijkstra’s weakest preconditions go random”

WEAKEST PRE-EXPECTATIONS



Dexter Kozen, Annabelle McIver, and Carroll Morgan

From predicates to quantities


- Let program P be:

$x := x+5 \quad [4/5] \quad x := 10$

The expected value of x on P 's termination is:

$$\frac{4}{5} \cdot (x + 5) + \frac{1}{5} \cdot 10 = \frac{4x}{5} + 6$$

initial value
of x



From predicates to quantities

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$x := x+5 \quad [4/5] \quad x := 10$

The expected value of x on P 's termination is:

$$\frac{4}{5} \cdot (x + 5) + \frac{1}{5} \cdot 10 = \frac{4x}{5} + 6$$

- The probability that $x = 10$ on P 's termination is:

$$\frac{4}{5} \cdot \underbrace{[x+5 = 10]}_{\text{Iverson brackets}} + \frac{1}{5} \cdot 1 = \frac{4 \cdot [x = 5] + 1}{5}$$

Expectations

The set of **expectations**² (read: random variables):

$$\mathbb{E} = \left\{ f \mid f : \underbrace{\mathbb{S}}_{\text{states}} \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\} \right\}$$

² ≠ expectations in probability theory.

Expectations

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Examples: $[x = 5]$ $\frac{4x}{5} + 6$ $\frac{4 \cdot [x=5] + 1}{5}$ **1** $x^2 + \sqrt{(y+1)} \dots$

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Examples: $[x = 5]$ $\frac{4x}{5} + 6$ $\frac{4 \cdot [x=5] + 1}{5}$ $\mathbf{1}$ $x^2 + \sqrt{y+1} \dots$

$(\mathbb{E}, \sqsubseteq)$ is a **complete lattice** where $f \sqsubseteq g$ if and only if $\forall s \in \mathbb{S}. f(s) \leq g(s)$

expectations are the **quantitative analogue** of predicates

² ≠ expectations in probability theory.

Weakest pre-expectations

For program P , let $wp[[P]] : \mathbb{E} \rightarrow \mathbb{E}$ an expectation transformer

$g = wp[[P]](f)$ is P 's **weakest pre-expectation** w.r.t. post-expectation f iff
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For program P , let $wp\llbracket P \rrbracket : \mathbb{E} \rightarrow \mathbb{E}$ an expectation transformer

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the expected value of f after executing P on input s equals $g(s)$

Examples:

For $P:: x := x+5 \quad [4/5] \quad x := 10$, we have:

$$wp\llbracket P \rrbracket(x) = \frac{4x}{5} + 6 \quad \text{and} \quad wp\llbracket P \rrbracket([x = 10]) = \frac{4 \cdot [x = 5] + 1}{5}$$

$wp\llbracket P \rrbracket([\varphi])$ is the probability of predicate φ on P 's termination
 $wp\llbracket P \rrbracket(\mathbf{1})$ is P 's termination probability

Kozen's duality theorem

$wp[[P]](f)(s)$ is the expected value of f after running P on input s

Let μ_P^s be the distribution over P 's final states when P starts in s .

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Then for post-expectation f : $\underbrace{wp[[P]](f)(s)}_{\text{"backward"}} = \underbrace{\sum_{t \in \mathbb{S}} \mu_P^s(t) \cdot f(t)}_{\text{"forward"}}$

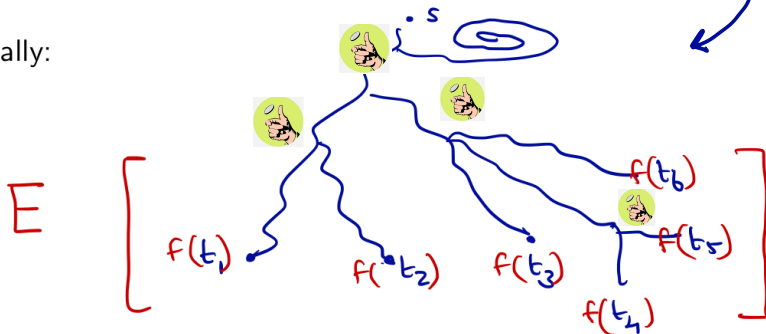
Kozen's duality theorem

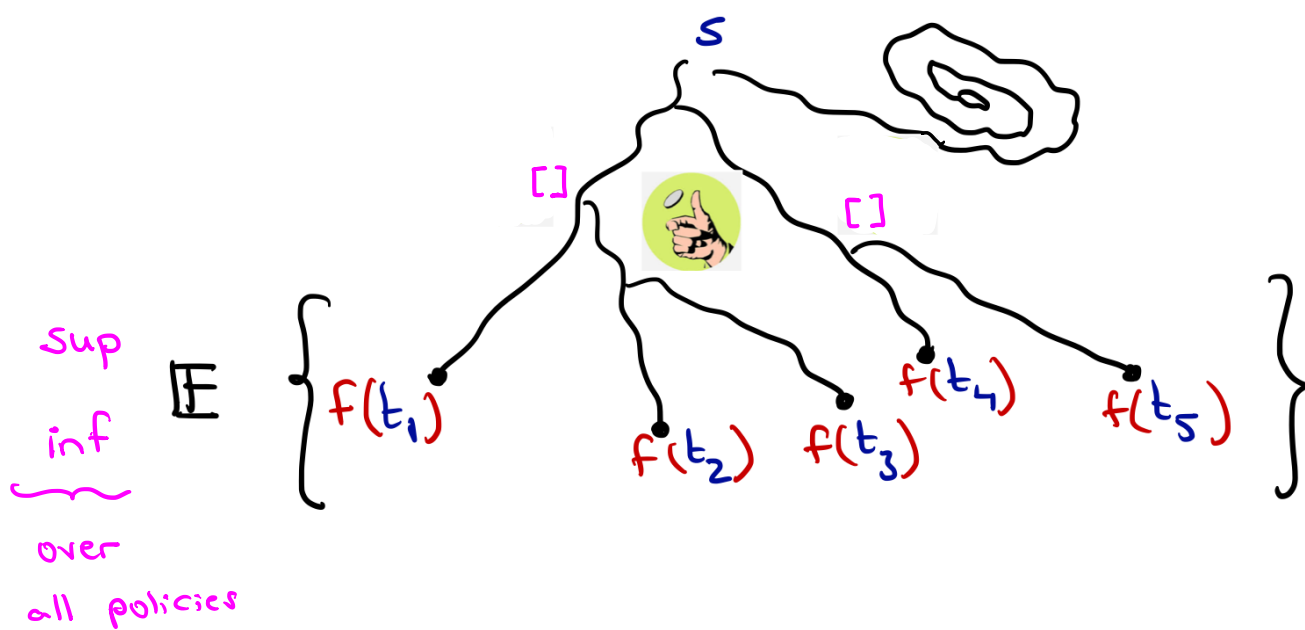
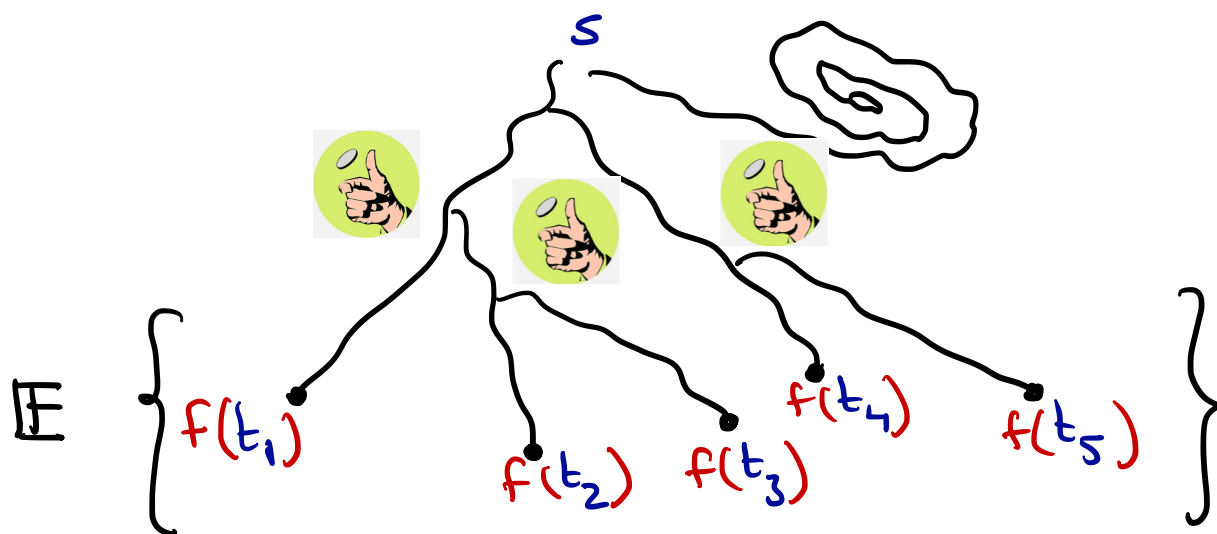
$wp\llbracket P \rrbracket(f)(s)$ is the expected value of f after running P on input s

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Pictorially:





How to obtain wp for a program?

Syntax probabilistic program P

skip

$x := E$

$x \approx \mu$

$P; Q$

Semantics $wp[[P]](f)$

substitution

f
 $f[x := E]$

$$\lambda s. \int_{\mathbb{Q}} (\lambda v. f(s[x := v])) d\mu_s$$

$wp[[P]](wp[[Q]](f))$

backwards!

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$wp[[P]](wp[[Q]](f))$

$[\varphi] \cdot wp[[P]](f) + [\neg\varphi] \cdot wp[[Q]](f)$

$p \cdot wp[[P]](f) + (1-p) \cdot wp[[Q]](f)$

How to obtain wp for a program?

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if (φ) P else Q

$P[p] Q$

while (φ) $\{P\}$

Semantics $wp\llbracket P \rrbracket(f)$

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$wp\llbracket P \rrbracket(wp\llbracket Q \rrbracket(f))$

$[\varphi] \cdot wp\llbracket P \rrbracket(f) + [\neg\varphi] \cdot wp\llbracket Q \rrbracket(f)$

$p \cdot wp\llbracket P \rrbracket(f) + (1-p) \cdot wp\llbracket Q \rrbracket(f)$

$\text{lfp } X. \underbrace{([\varphi] \cdot wp\llbracket P \rrbracket(X)) + [\neg\varphi] \cdot f}_{\text{loop characteristic function } \Phi_f(X)}$

where lfp is the least fixed point wrt. the ordering \sqsubseteq on \mathbb{E} .

Examples

1. Consider again program P :

$x := x+5 \quad [4/5] \quad x := 10$

For $f = x$, we have:

$$\begin{aligned}
 wp[[P]](x) &= \frac{4}{5} \cdot wp[[x := 5]](x) + \frac{1}{5} \cdot wp[[x := 10]](x) \\
 &= \frac{4}{5} \cdot (x+5) + \frac{1}{5} \cdot 10 = \boxed{\frac{4x}{5} + 6}
 \end{aligned}$$

(Note: In the original image, a red circle highlights $f = x$ and a curved arrow points from $x+5$ to the 5 in the first term of the equation.)

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 \end{aligned}$$

2. For program P (again) and $f = [x = 10]$, we have:

$$\begin{aligned}
 wp[[P]]([x=10]) &= \frac{4}{5} \cdot wp[[x := x+5]]([x=10]) + \frac{1}{5} \cdot wp[[x := 10]]([x=10]) \\
 &= \frac{4}{5} \cdot [x+5 = 10] + \frac{1}{5} \cdot [10 = 10] \\
 &= \boxed{\frac{4 \cdot [x = 5] + 1}{5}}
 \end{aligned}$$

Loops

$$wp\llbracket \text{while } (\varphi) \{ P \} \rrbracket (f) = \text{lfp } X. \underbrace{([\varphi] \cdot wp\llbracket P \rrbracket(X) + [\neg\varphi] \cdot f)}_{\text{loop characteristic function } \Phi_f(X)}$$

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- ▶ Function $\Phi_f : \mathbb{E} \rightarrow \mathbb{E}$ is **Scott continuous** on $(\mathbb{E}, \sqsubseteq)$
- ▶ By Kleene's fixed point theorem: $\text{lfp } \Phi_f = \sup_{n \in \mathbb{N}} \Phi_f^n(\mathbf{0})$
- ▶ $\Phi_f^n(\mathbf{0})$ is f 's expected value after n times running P , starting in $\mathbf{0}$

Examples

```
x := 1;
while (x > 0) {
  x +:= 2 [1/2] x -:= 1
}
```

post-expectation: **1**

```
x := geometric(1/4);
y := geometric(1/4);
t := x+y+1 [5/9] t := x+y;
r := 1;
for i in 1..3 {
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Examples

weakest pre-expectation: $\frac{\sqrt{5}-1}{2}$

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post-expectation: [**r = 1**]

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weakest pre-expectation: $\frac{1}{\pi}$

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post-expectation: **[r = 1]**

Probabilistic weakest liberal preconditions

Restrict f to denote probabilities, i.e., $f(s) \leq 1$ for each state s

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Loops under wlp:

$$wlp[\text{while } (\varphi) \{ P \}](f) = \text{gfp } X. \underbrace{([\varphi] \cdot wlp[P](X) + [\neg\varphi] \cdot f)}_{\text{loop characteristic function } \Phi_f(X)}$$

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Relating weakest liberal preconditions to wp:

$$wlp\llbracket P \rrbracket(f) = wp\llbracket P \rrbracket(f) + \underbrace{(1 - wp\llbracket P \rrbracket(\mathbf{1}))}_{\text{probability that } P \text{ diverges}}$$

partial correctness total correctness

Probabilistic weakest liberal preconditions

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Loops under wlp:

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If program P is AST:

$$wlp\llbracket P \rrbracket(f) = wp\llbracket P \rrbracket(f) + \underbrace{(1 - wp\llbracket P \rrbracket(1))}_{=1} = wp\llbracket P \rrbracket(f)$$

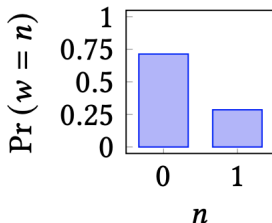
Bayesian learning by example

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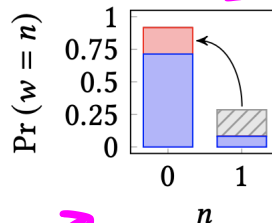
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```



prior



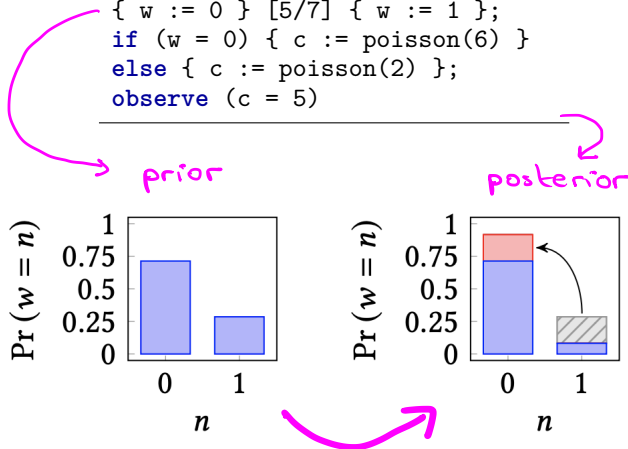
posterior

Bayesian learning by example

```

{ w := 0 } [5/7] { w := 1 };
if (w = 0) { c := poisson(6) };
else { c := poisson(2) };
observe (c = 5)

```



Probability mass is **normalised** by the probability of feasible runs

Learning [Nori *et al*, AAI 2014; Olmedo, K., *et al*, TOPLAS 2018]

The probability of feasible program runs:

$$wp[[P]](\mathbf{1}) = 1 - Pr\{P \text{ violates an observation}\}$$

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Weakest pre-expectation of observations:

$$wp[[\text{observe } \varphi]](\textcolor{red}{f}) = [\varphi] \cdot \textcolor{red}{f}$$

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Normalisation:

$$\frac{wp[P](f)}{wp[P](1)}$$

Learning [Nori *et al*, AAI 2014; Olmedo, K., *et al*, TOPLAS 2018]

The probability of feasible program runs:

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Normalisation:

$$\frac{wp\llbracket P \rrbracket(\textcolor{red}{f})}{wp\llbracket P \rrbracket(\mathbf{1})}$$

Fine point: under possible program divergence: $\frac{wp\llbracket P \rrbracket(\textcolor{red}{f})}{wlp\llbracket P \rrbracket(\mathbf{1})}$

Extensions of probabilistic wp

- ▶ for **recursion** [LICS 2016]
- ▶ for **exact inference** [TOPLAS 2018]
- ▶ for **continuous** distributions [SETTS 2019]
- ▶ for **probabilistic separation logic** [POPL 2019]
- ▶ for **weighted** programs [OOPSLA 2022]
- ▶ for **expected runtime** analysis [JACM 2018]
- ▶ for **amortised runtime** analysis [POPL 2023]

HOW TO TREAT LOOPS?



Upper bounds

Recall:

$$wp\llbracket \text{while } (\varphi) \{ P \} \rrbracket (f) = \text{lfp } X. \underbrace{([\varphi] \cdot wp\llbracket P \rrbracket(X) + [\neg\varphi] \cdot f)}_{\Phi_f(X)}$$

By Park's lemma: for $\text{while}(\varphi)\{P\}$ and expectations f and l :

$$\underbrace{\Phi_f(l) \sqsubseteq l}_{\text{"upper" invariant } l} \quad \text{implies} \quad \underbrace{wp\llbracket \text{while}(\varphi)\{P\} \rrbracket (f) \sqsubseteq l}_{\text{lfp } \Phi_f}$$

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Example: `while(c = 0) { x++ [p] c := 1 }`

$$l = x + [c = 0] \cdot \frac{p}{1-p} \text{ is an "upper"-invariant w.r.t. } f = x$$

Lower bounds

[Hark, K. *et al*, POPL 2020]

$$\left(l \sqsubseteq \Phi_f(l) \wedge \text{side conditions} \right) \text{ implies } l \sqsubseteq \text{lfp } \Phi_f$$

Lower bounds

[Hark, K. *et al*, POPL 2020]

$$(I \sqsubseteq \Phi_f(I) \wedge \underbrace{\text{side conditions}}) \text{ implies } I \sqsubseteq \text{lfp } \Phi_f$$

where the side conditions for the loop $\text{while}(\varphi)\{P\}$ are:

1. the loop is PAST, and
2. for any $s \models \varphi$, $\underbrace{wp[[P]](|I(s) - I|)(s)}_{\text{conditional difference boundedness}} \leq c$ for some $c \in \mathbb{R}_{\geq 0}$

Lower bounds

[Hark, K. *et al*, POPL 2020]

$$(\textcolor{blue}{I} \sqsubseteq \Phi_{\textcolor{red}{f}}(\textcolor{blue}{I}) \wedge \text{side conditions}) \text{ implies } \textcolor{blue}{I} \sqsubseteq \text{lf}p \Phi_{\textcolor{red}{f}}$$

where the side conditions for the loop $\text{while}(\varphi)\{P\}$ are:

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2. for any $s \models \varphi$, $\underbrace{wp[[P]](|\textcolor{blue}{I}(s) - \textcolor{blue}{I}|)(s)}_{\text{conditional difference boundedness}} \leq c$ for some $c \in \mathbb{R}_{\geq 0}$

Example. Program: $\text{while}(c = 0)\{x++[p]c := 1\}$ satisfies the conditions.

$$\textcolor{blue}{I} = x + [c = 0] \cdot \frac{p}{1-p} \text{ is a "lower"-invariant w.r.t. } \textcolor{red}{f} = x$$

A proof rule for AST

[McIver, K. *et al*, POPL 2018]

Consider the loop $\text{while}(\varphi)\{ \text{body} \}$ and let:

▶ $V : \mathbb{S} \rightarrow \mathbb{R}_{\geq 0}$ with $[\neg V] = [\neg \varphi]$

V indicates termination

▶ $p : \mathbb{R}_{\geq 0} \rightarrow (0, 1]$ antitone

p probability

▶ $d : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$ antitone

d decrease

$$\hookrightarrow x \leq y \longrightarrow d(y) \leq d(x)$$

A proof rule for AST

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If:

$$\underbrace{[\varphi] \cdot wp[[\text{body}]](V) \leq V}_{\text{expected value of } V \text{ does not decrease by an iteration}}$$

in

and

$$\underbrace{[\varphi] \cdot (p \circ V) \leq \lambda s. wp[[\text{body}]](|V \leq V(s) - d(V(s))|)(s)}_{\text{with at least prob. } p, V \text{ decreases at least by } d}$$

with at least prob. p , V decreases at least by d

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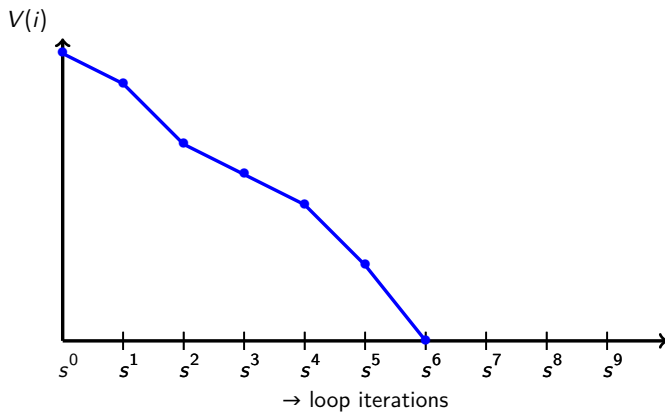
$$\underbrace{[\varphi] \cdot (p \circ V)}_{\text{with at least prob. } p, V \text{ decreases at least by } d} \leq \lambda s. wp[\text{body}] (| V \leq V(s) - d(V(s)) |) (s)$$

with at least prob. p , V decreases at least by d

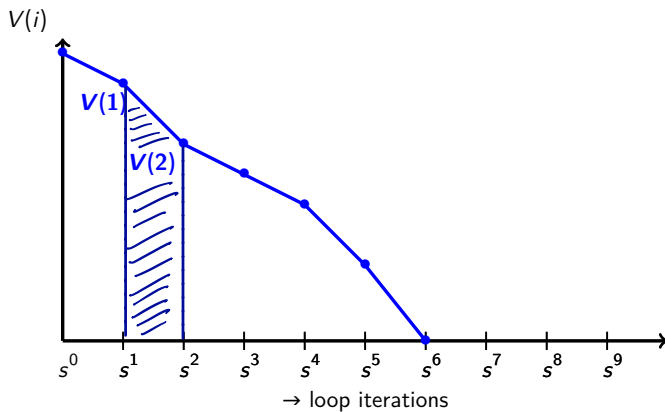
Then:

$$wp[\text{loop}](1) = 1 \quad \text{i.e., loop is AST}$$

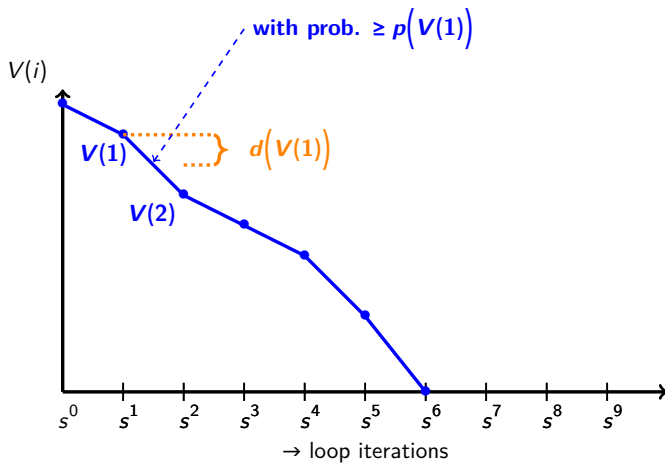
Intuition



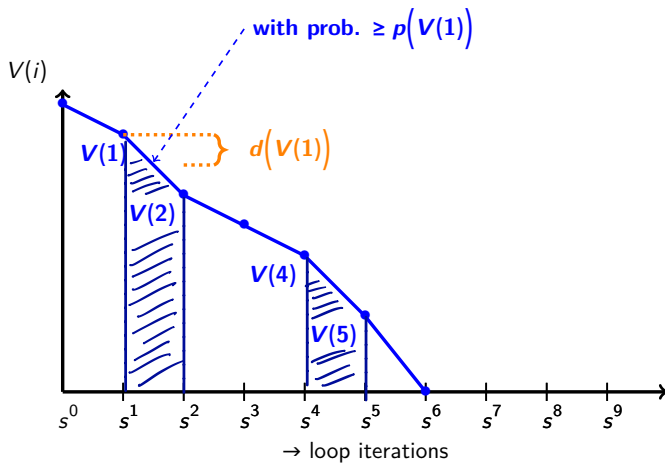
Intuition



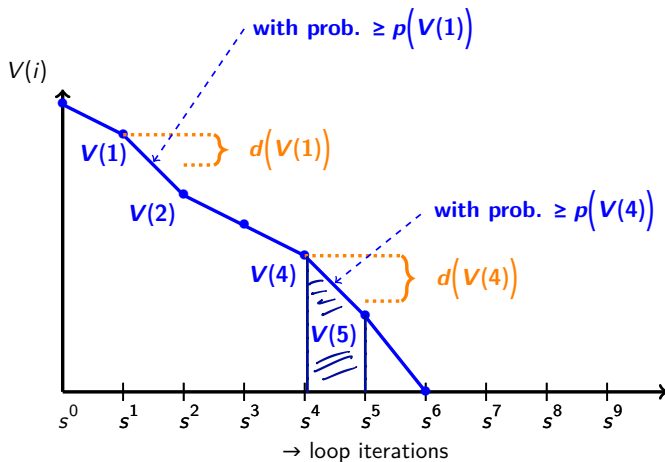
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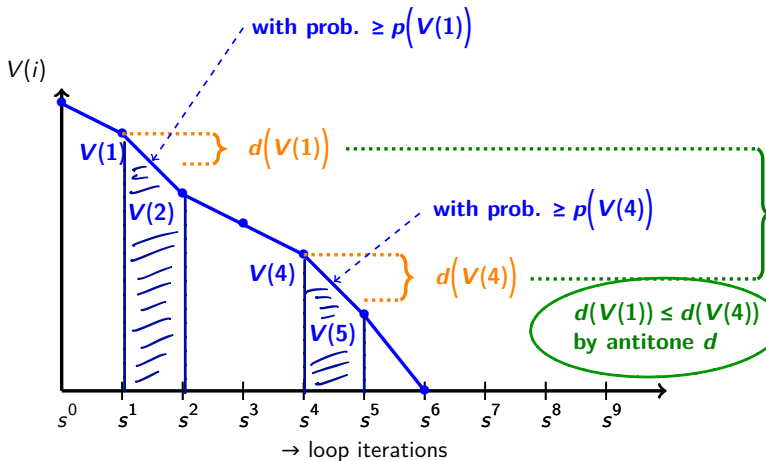
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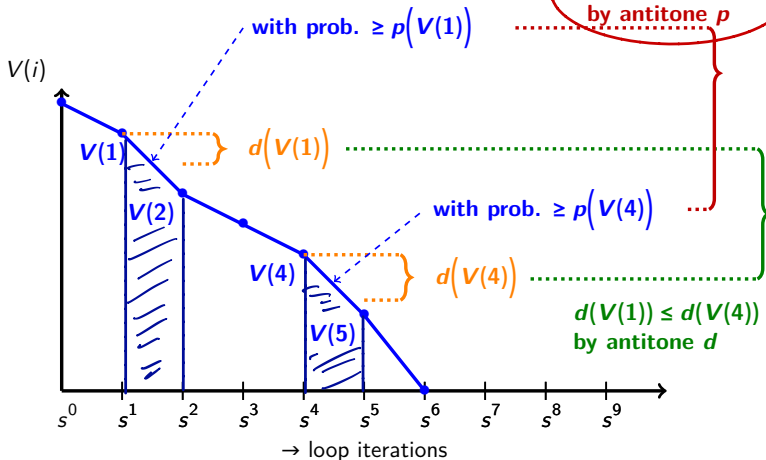
Intuition



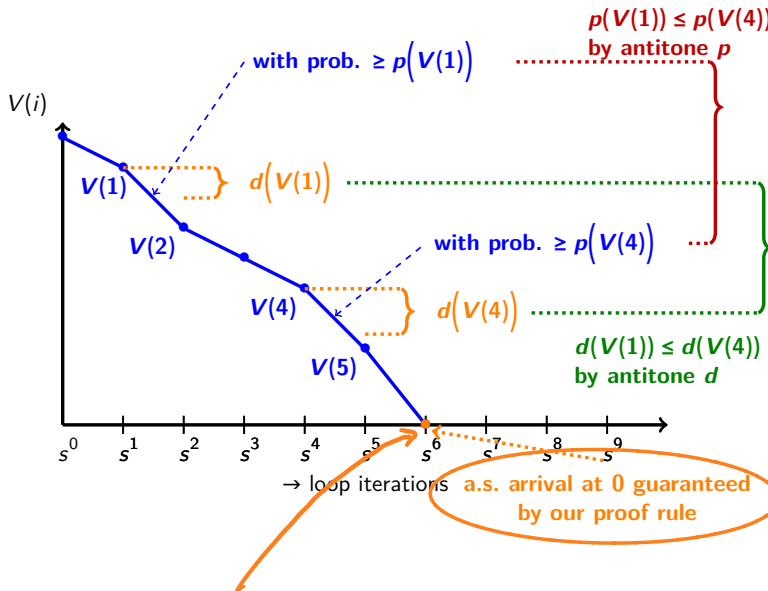
Intuition



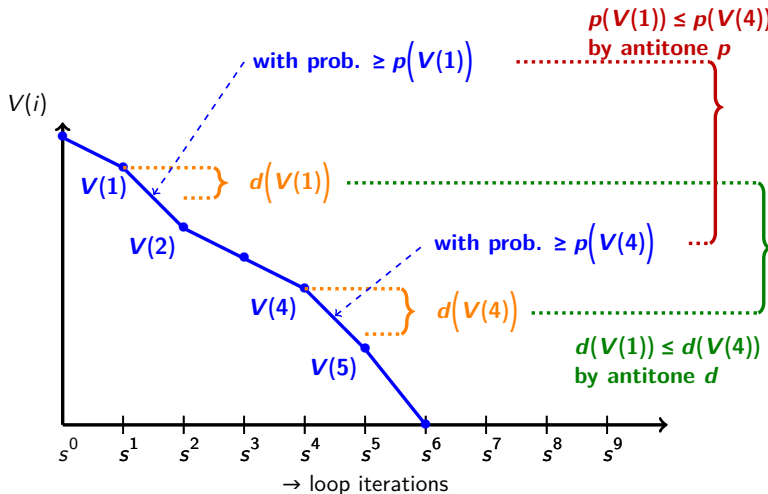
Intuition



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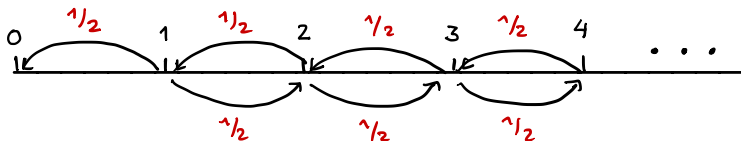
Intuition



The closer to termination, the more V decreases and this becomes more likely

Example: symmetric 1D random walk

```
while (x > 0) {
  x := x-1 [1/2] x := x+1
}
```



Example: symmetric 1D random walk

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while (x > 0) {  
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► Terminates almost surely

► Witness of almost-sure termination:

- $V = x$
- $p = 1/2$ and
- $d = 1$

Example: symmetric 1D random walk

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while (x > 0) {
  x := x-1 [1/2] x := x+1
}
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- ▶ Terminates almost surely

$1/2 - \epsilon$ is not AST



- ▶ Witness of almost-sure termination:

- ▶ $V = x$
- ▶ $p = 1/2$ and
- ▶ $d = 1$

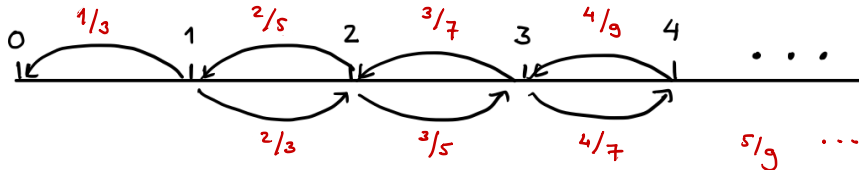
That's all you need to prove almost-sure termination!

Example: fair-in-the-limit 1D random walk

```

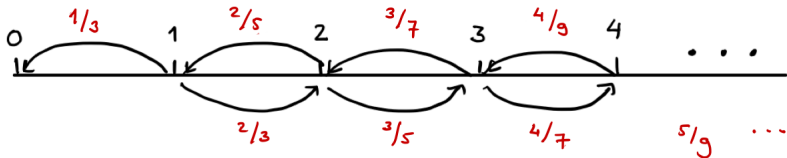
while (x > 0) {
  q := x/(2*x+1);
  x-- [q] x++
}

```



The closer to 0, the more unfair — drifting away from 0 — it gets

Example: fair-in-the-limit 1D random walk



► The closer to 0, the more unfair — drifting away from 0 — it gets

► Witness of almost-sure termination:

► $V = H_x$, the x -th Harmonic number $1 + 1/2 + \dots + 1/x$

►
$$d(v) = \begin{cases} 1/n & \text{if } H_{n-1} < v \leq H_n \\ 1 & \text{if } v = 0 \end{cases}, \text{ and}$$

► $p = 1/3$

So far we studied several proof rules to verify whether
a given expectation (or triple V, p, d) meets
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This can be extended to expected runtimes too

e.g. proving PAST

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This can be extended to expected runtimes too

To automate, we need a **concrete syntax** for expectations!

RELATIVE COMPLETENESS

SIAM J. COMPUT.
Vol. 7, No. 1, February 1978

SOUNDNESS AND COMPLETENESS OF AN AXIOM SYSTEM FOR PROGRAM VERIFICATION*

STEPHEN A. COOK†

Abstract. A simple ALGOL-like language is defined which includes conditional, while, and procedure call statements as well as blocks. A formal interpretive semantics and a Hoare style axiom system are given for the language. The axiom system is proved to be sound, and in a certain sense complete, relative to the interpretive semantics. The main new results are the completeness theorem, and a careful treatment of the procedure call rules for procedures with global variables in their declarations.

Key words. program verification, semantics, axiomatic semantics, interpretive semantics, consistency, completeness

1. Introduction. The axiomatic approach to program verification along the lines formulated by C. A. R. Hoare (see, for example, [6] and [7]) has received a great deal of attention in the last few years. My purpose here is to pick a simple programming language with a few basic features, give a Hoare style axiom system for the language, and then give a clean and careful justification for both the soundness and adequacy (i.e., completeness) of the axiom system. The justification is done by introducing an interpretive semantics for the language, rather like that in [10] and [8]. These two papers also have outlined soundness arguments for axiom systems, but for somewhat different language features, axioms, and interpretive models. The completeness claim and argument presented here is new (although completeness and incompleteness proofs inspired by an earlier version of this paper [2] appear in [3], [11], [12], [13], and [14]). I have tried to choose the axioms and rules of the formal system to be as simple as possible, subject to the constraints that they be sound, complete, and in the style and spirit of Hoare's rules.



Stephen Cook

SIAM J. on Computing, 1978

Relative complete verification

Ordinary Programs

$F \in \text{FO-Arithmetic}$

implies

$wp[[P]](F) \in \text{FO-Arithmetic}$

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modulo an oracle for deciding \implies

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Probabilistic Programs

$f \in \text{SomeSyntax}$

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between two syntactic expectations.

Q: How does the **SomeSyntax** look like?

50 years of Hoare logic

“Completeness is a subtle manner and requires a careful analysis”



Krzysztof R. Apt



Ernst-Rüdiger Olderog

Requirements on a syntax

$$\frac{1}{\pi}$$

$$\frac{\sqrt{5}-1}{2}$$

```
x := 1;
while (x > 0) {
  x += 2 [1/2] x -= 1
}
```

1

```
x := geometric(1/4);
y := geometric(1/4);
t := x+y+1 [5/9] t := x+y;
r := 1;
for i in 1..3 {
  s := 0
  for j in 1..2t {
    s := s+1 [1/2] skip
  }
  r := (s == t)
}
```

[r = 1]

rational numbers, algebraic numbers, transcendental numbers, etc.

Syntax of expectations

- The set **Exp** of syntactic expectations

f	\longrightarrow	a	arithmetic expressions
		$[\varphi] \cdot f$	guarding
		$f + f$	addition
		$f \cdot f$	multiplication
		$\mathcal{S}_x:f$	<u>supremum</u> over variable x
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- Examples:

$\mathcal{E}_x: [x \cdot x < y] \cdot x$

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$$\mathcal{Z}_x: [x \cdot x < y] \cdot x \equiv \sqrt{y}$$

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- Examples:

$$\mathcal{E}_x: [x \cdot x < y] \cdot x \equiv \sqrt{y}$$

$$\mathcal{E}_z: [z \cdot (x + 1) = 1] \cdot z \equiv \frac{1}{x + 1}$$

Examples

- ▶ polynomials $y + x^3 + 2x^2 + x - 7$ widely used as templates
- ▶ rational functions $\frac{x^2 - 3x + 4}{y^2 \cdot x - 3y + 1}$
- ▶ square roots \sqrt{x}
- ▶ irrational, algebraic and transcendental numbers $\frac{\sqrt{5}-1}{2}, \pi, e, \dots$
- ▶ Harmonic numbers $H_k = \sum_{k=1}^x \frac{1}{k}$ used in run-time/termination analysis

Expressiveness

[Batz, K. *et al*, POPL 2021]

The set Exp of syntactic expectations is **expressive**.

For all pGCL programs P and $f \in \text{Exp}$ it holds:

$$wp[[P]](\llbracket f \rrbracket) = \llbracket g \rrbracket$$

for some syntactic expectation $g \in \text{Exp}$.

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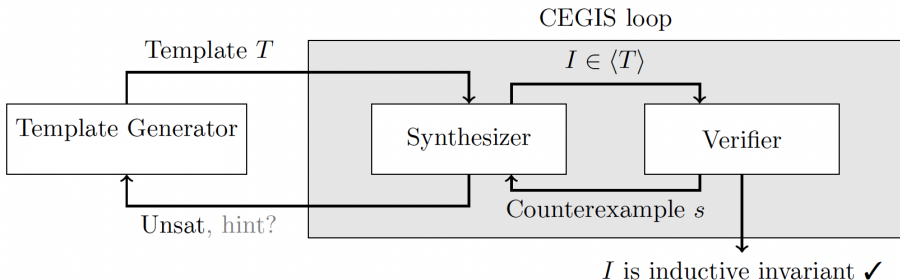
for some syntactic expectation $g \in \text{Exp}$.



Expressiveness does not mean decidability, e.g.,
for $f, g \in \text{Exp}$, does $\![g]\! \sqsubseteq wp[\![P]\!](\![f]\!)$ is **undecidable**

Inductive invariant synthesis

Automated synthesis of inductive invariants



Bounded retransmission protocol

[Helmink *et al*, 1993]

- ▶ Send file of $N \approx 10^{10}$ packets via **lossy** channel
- ▶ Packet **loss probability** $\frac{1}{100}$, say
- ▶ # packet retransmissions ≤ 10 ; otherwise file transmission **fails**

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```

sent := 0; fail := 0;
while ( sent < N ∧ fail < F ) {
  { fail := fail + 1 } [0.01] { fail := 0; sent := sent + 1 }
  failed transmission
  successful transmission
}

```

Bounded retransmission protocol

[Helmink *et al*, 1993]

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BRP

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```

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```

failed transmission

successful transmission

We verify $wp[[BRP]]([fail = 10]) \leq \frac{1}{1000}$ in 11 seconds. Fully automatically.

Impossible for probabilistic model checkers!

50/61

Synthesising inductive invariants

Problem: find a piece-wise linear inductive invariant I s.t.

$$\underbrace{\Phi_f(I) \sqsubseteq I \text{ and } I \sqsubseteq g}_{I \text{ is inductive for } f \text{ and } g} \quad \text{or determine there is no such } I$$

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Approach: use **template-based** invariants of the (simplified) form:

$$T = [b_1] \cdot a_1 + \dots + [b_k] \cdot a_k$$

with

- ▶ b_i is a boolean combination of linear inequalities over program vars
- ▶ a_i a linear expression over the program variables with $[b_i] \cdot a_i \geq 0$
- ▶ the b_i 's partition the state space, i.e., $s \models b_i$ for a unique i

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Example: $[c=1] \cdot (2 \cdot x + 1) + [c \neq 1] \cdot x$ is in the above form,
and $[x \geq 1] \cdot x + [x \geq 2] \cdot y$ can be rewritten into it.

Checking linear entailments

[K., Mclver *et al*, SAS 2010]

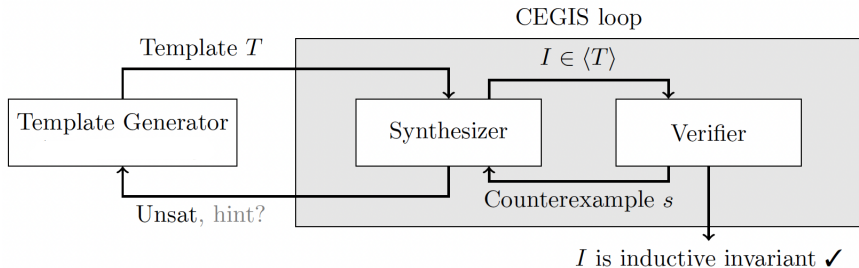
For piecewise linear expectations:

$$f = [b_1] \cdot a_1 + \dots + [b_k] \cdot a_k \quad \text{and} \quad g = [c_1] \cdot e_1 + \dots + [c_m] \cdot e_m$$

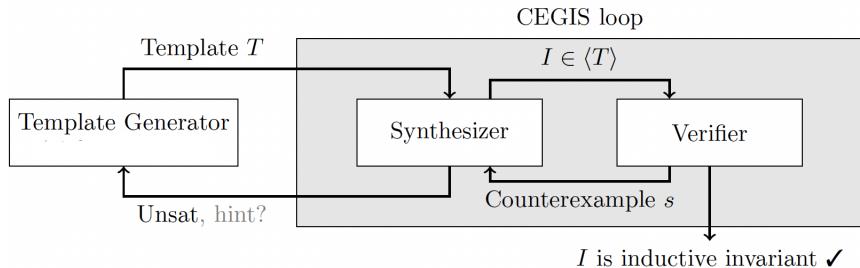
it is decidable whether the quantitative entailment $f \sqsubseteq g$ holds

$$f \sqsubseteq g \quad \text{if and only if} \quad \underbrace{\bigwedge_{i=1}^k \bigwedge_{j=1}^m (b_i \wedge c_j) \rightarrow a_i \sqsubseteq e_j}_{\text{formula in quantifier-free linear arithmetic}} \quad \text{is valid}$$

CEGIS for probabilistic invariants [Batz, K. et al, TACAS 2023]

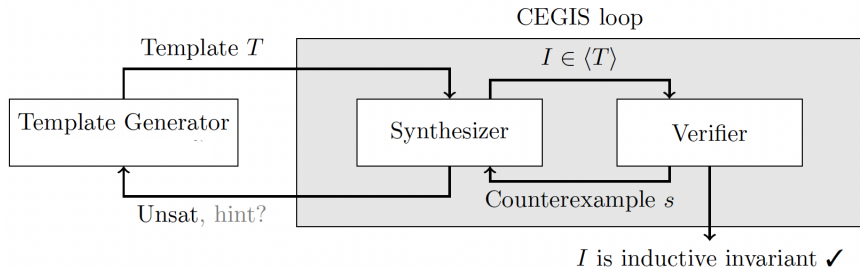


CEGIS for probabilistic invariants [Batz, K. et al, TACAS 2023]



- ▶ For **finite-state** programs, synthesis is **sound and complete**
- ▶ Applicable to **lower bounds**: UPAST and difference boundedness
- ▶ Uses SMT with QF-LRA (the synthesiser) and QF-LIRA (the verifier)

CEGIS for probabilistic invariants [Batz, K. et al, TACAS 2023]



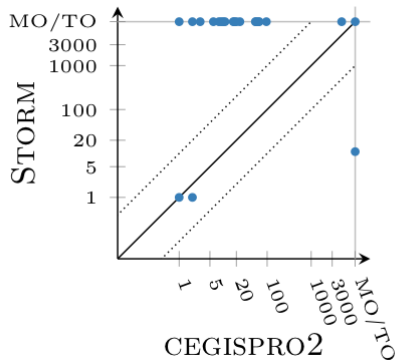
- ▶ For **finite-state** programs, synthesis is **sound and complete**
- ▶ Applicable to **lower bounds**: UPAST and difference boundedness
- ▶ Uses SMT with QF-LRA (the synthesiser) and QF-LIRA (the verifier)

CEGISPRO2 tool: <https://github.com/moves-rwth/cegispro2>

check it out !

Experiments

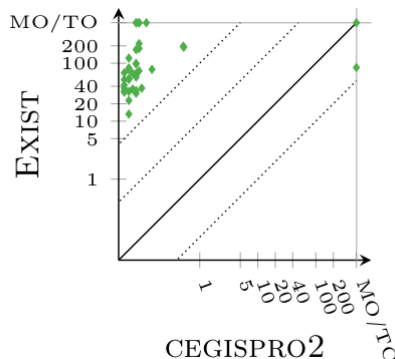
Comparison to
model checking



Synthesis of upper bounds
for finite-state programs

TO = 2h, MO = 8GB

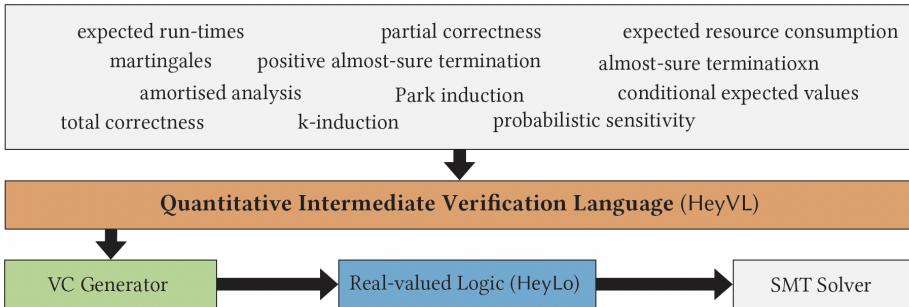
Comparison to an
ML technique



Synthesis of lower bounds

TO = 5min

Outlook: a probabilistic Dafny?



Caesar: A verification infrastructure for probabilistic programs

caesarverifier.org

← check it out!

A big thanks to my co-workers!



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